

# CheckStar Multi - User Instructions

Getting started with your in-line rotary torque transducer.

Manufacturer: Address:

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Declares that this product has been assessed and complies with the requirements of the relevant CE Directives when used with Crane Electronics Ltd readout devices.

## **SUMMARY**

The CheckStar Multi transducer is designed to measure the torque output of any non-impact assembly tool. The unique construction (patented) gives long brush life with minimal maintenance requirements. The transducer is compatible with the TorqueStar and IQVu Crane readout devices. The CheckStar Multi provides data, of nominal rating, transducer serial number and recommended re-calibration date (automatic recognition), when used with a compatible readout.

An alternative version is available with an angle measurement encoder which allows the measurement of the angle rotation in addition to torque, with a compatible readout unit.

The CheckStar Multi has a light ring that can be used to indicate fastening status with colours Amber, Green and Red.

## **OPERATION**

Select a suitable size of CheckStar Multi appropriate to the maximum torque rating of the tool to be used. The female square of the CheckStar Multi should be secured onto the tool output drive using the supplied pin and retaining ring. A socket should be fitted to the male square drive and secured via the spring loaded pin.

Connect to the readout, select an appropriate operating mode and then operate the tool in the normal way. In the interests of accuracy it is essential to maintain the correct alignment between the fastener, CheckStar and power tool. When using CheckStar rotary transducers with a tool and reaction bar the effective radial position of the reaction point should not be less than the figures given in Table 1 (see reverse). Failure to observe this requirement and also the maximum torque rating, may cause irreversible damage to the CheckStar.

The CheckStar rotary transducer with angle encoder may also be used with any tool except impact types. Angle measurements may be made with impulse tools but restriction on the maximum acceptance speed of the readout may limit accuracy. Since the angle encoder measures the angular position of the torsion shaft relative to the transducer body, it is important that the body is held still and does not rotate as the tool is operated.

If the male square spring pin is not required, this may be removed with a stepped (for location purposes) punch of  $\emptyset$ 2.3mm for the 1/4",  $\emptyset$ 3.95mm for the 3/8" or 1/2" squares and  $\emptyset$ 6.3mm for 3/4" or 1" square drives.

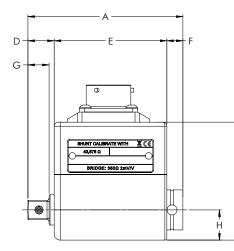


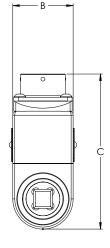
# NOTICE

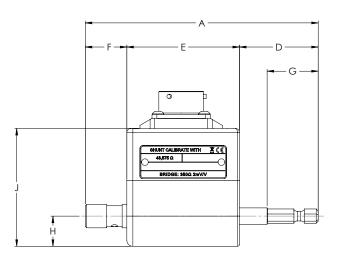
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# **CheckStar Multi - Dimensions and Weights**







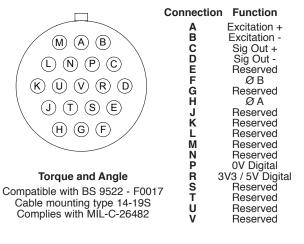
### **Dimensions in millimeters**

Drive	Α	в	с	D	Е	F	G	н	J	Weight (Grams)
1⁄4" Hex	115.8	30.0	73.0	39.2	56.0	20.6	25.5	13.2	54.5	210
1⁄4" Sq	71.5	30.0	73.0	10.3	56.0	5.2	7.3	13.2	54.5	200
∛" Sq	77.0	30.0	77.1	12.9	56.0	8.1	10.5	15.0	58.6	240
½" Sq	87.0	42.0	88.0	17.0	58.0	12.0	14.7	21.0	69.5	430
³⁄₄" Sq	106.0	52.0	98.6	25.3	60.0	20.7	21.4	26.0	80.1	760
1" Sq	125.0	63.0	110.1	31.8	64.5	28.7	26.0	32.0	91.6	1500
1½" Sq	181.0	102.0	153.7	43.8	86.5	50.7	39.3	51.0	136.0	5700

#### Table 1

		Maximu	IM RPM	Angle ver	Min. radial position of		
Drive Size/Type	Rating (Nm)	Continuous	Intermittent	Resolution Degrees	Max RPM	reaction bar at Max torque (mm)	
1/4" Hex	2	5000	11,000	0.125	2500	50	
1/4" Hex	5	5000	11,000	0.125	2500	50	
1⁄4" Sq.	5	5000	11,000	0.125	2500	50	
1/4" Hex	10	5000	11,000	0.125	2500	50	
1⁄4" Sq.	10	5000	11,000	0.125	2500	50	
1/4" Hex	20	5000	11,000	0.125	2500	100	
1⁄4" Sq.	20	5000	11,000	0.125	2500	100	
³⁄₀" Sq.	25	2500	10,000	0.125	2500	50	
³⁄8" Sq.	50	2500	10,000	0.125	2500	100	
³⁄₀" Sq.	75	2500	10,000	0.125	2500	150	
1⁄2" Sq.	180	2500	7,600	0.125	2500	180	
<sup>3</sup> ⁄ <sub>4</sub> " Sq.	250	2000	5,000	0.125	2000	120	
<sup>3</sup> ⁄4" Sq.	500	2000	5,000	0.125	2000	240	
1" Sq.	750	1000	4,400	0.125	1000	190	
1" Sq.	1400	1000	4,400	0.125	1000	350	
1½" Sq.	3000	1000	4,400	0.125	500	310	
1½" Sq.	5000	1000	4,400	0.125	500	520	

Continuous duty is defined as 100% duty in either direction and intermittent duty as 10% of that working time. All torque equipment should be re-calibrated every 12 months.



#### Specifications

Bridge resistance	-	350 ohm
Output sensitivity	-	2mV/V
Static accuracy	-	± 0.25% fsd
Stability of zero offset with		
temperature	-	± 0.01% of fsd./°C
Overload Capacity	-	125% f.s.d
Operation to specification over a		
temperature range of	-	+5 to +40°C
Operation to reduced specification		
over a temperature range of	-	-10 to +60°C
Humidity 10 to 75% non-condensing Ingress Protection of the transducer		
(except connector)	-	IP40

The male and female square drives are designed to be compatible with drives meeting the specifications of:-ANSI B107-4 - 1982; BS4006 - 1992; DIN 3121 - 1987

For more information about the CheckStar Multi torque transducer, please call +44 (0) 1455 25 14 88 or email us at <u>sales@crane-electronics.com</u>.



## Locations

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